

#### Communication-capable globe valve actuator with emergency control function for 2-way and 3-way globe valves

- Actuating force 2000 N
- Nominal voltage AC/DC 24 V
- Control modulating
- Nominal stroke 32 mm
- Communication via LONWORKS®
   (FTT-10A)
- Conversion of sensor signals
- Integrated temperature controller
- Design life SuperCaps 15 years

# **Technical data**



# **AVK24ALON**





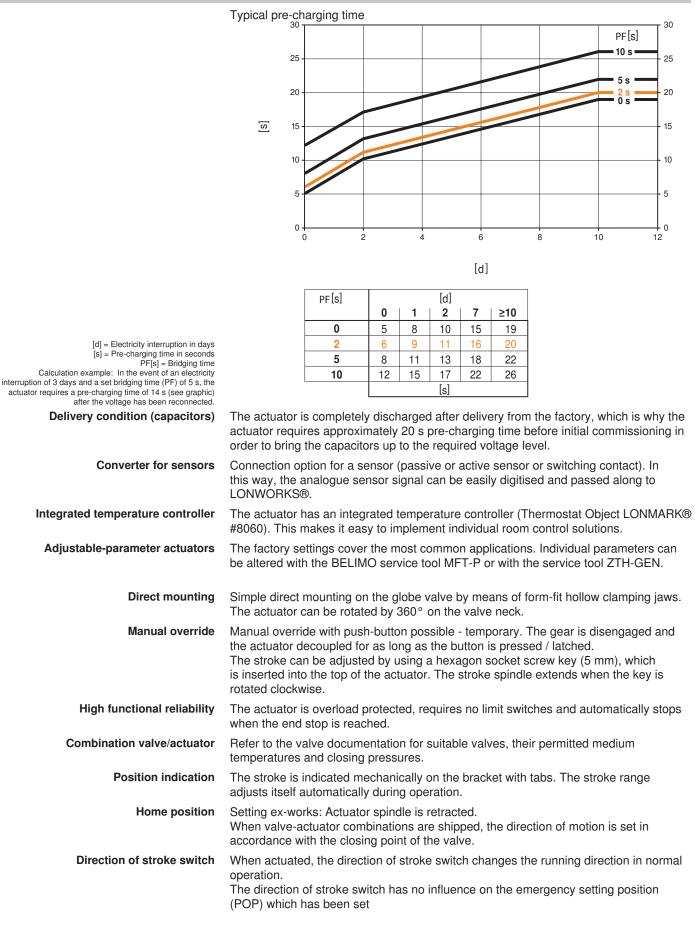
Electrical data	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Nominal voltage range	AC 19.228.8 V / DC 21.628.8 V
	Power consumption in operation	5 W
	Power consumption at rest	2 W
	Power consumption for wire sizing	9.5 VA
	Connection supply / control	Cable 1 m, 6 x 0.75 mm <sup>2</sup>
Data for LONWORKS®	Certified	According to LONMARK® 3.3
	Processor	Neuron 3150
	Transceiver	FTT-10A, compatible with LPT-10
	Functional Profile as per LONMARK®	Damper actuator object #8110
		Open Loop Sensor Object #1
	INC plug in for actuator / appagr /	Thermostat Object #8060
	LNS plug-in for actuator / sensor / controller	Can be run with any LNS-based integration tool (min. for LNS 3.x)
	Service button and status LED	According to LONMARK® guidelines
	Conductors, cables	Signal cable lengths, cable specifications and
		topology of the LONWORKS® network in
		accordance with the ECHELON® guidelines
Functional data	Actuating force	2000 N
i unotional data	Position feedback U	DC 210 V
	Position feedback U note	Max. 0.5 mA
	Position feedback U variable	Start point DC 0.5 8V
		End point DC 2.5 10V
	Setting emergency setting position	Actuator spindle 0100%, adjustable (POP rotary knob)
	Bridging time (PF) variable	110 s
	Position accuracy	5% absolute
	Manual override	Gear disengagement with push-button
	Nominal stroke	32 mm
	Actuating time	150 s / 32 mm
	Variable actuating time	35150 s / 32 mm
	Actuating time emergency control	35 s / 32 mm
	function	
	Override control, controllable via	MAX (maximum position) = 100%
	nviManOvrd	MIN (minimum position) $= 0\%$
		ZS (intermediate position) = 50%
	Override control, controllable via nviManOvrd, modifiable	ZS = MINMAX
	Sound power level motor max.	60 dB(A)
	Sound power level motor note	55 dB (A) @ 90 s running time
	Sound power level emergency setting position max.	60 dB(A)
	Position indication	Mechanical 5 32 mm stroke
Safety	Protection class IEC/EN	III Safety extra-low voltage
	Degree of protection IEC/EN	IP54
	EMC	CE according to 2004/108/EC
	Certification IEC/EN	Certified to: IEC/EN 60730-1 and IEC/EN 60730-2-14

AVK24ALON	Globe valve actuator, communica AC/DC 24 V, 2000 N	ative, modulating, BELIMO
Technical data		
Safety	Principle of operation Rated impulse voltage supply / control	Type 1.AA 0.8 kV
	Control pollution degree Ambient temperature Non-operating temperature	3 050°C -4080°C
	Ambient humidity Maintenance	95% r.h., non-condensing Maintenance-free
Weight	Weight approx.	4.460 kg
Safety notes		
	<ul> <li>air-conditioning systems and is not a application, especially not in aircraft</li> <li>Only authorised specialists may carrinstitutional installation regulations in</li> <li>The switch for changing the direction only by authorised personnel. The d connection with frost protection circl.</li> <li>The device may only be opened at t parts that can be replaced or repaired.</li> <li>The cable must not be removed from</li> <li>The device contains electrical and e</li> </ul>	he manufacturer's site. It does not contain any ed by the user.
Product features		
Principle of operation	The actuator is equipped with an integrated interface for LONWORKS®. The actuator can be integrated and connected directly with LONWORKS® via transceiver FTT-10A. Interrupting the supply voltage causes the valve to be moved to the selected emergency setting position (POP) by means of stored electrical energy.	
Pre-charging time (start up)	<ul> <li>The capacitor actuators require a pre-charging time. This time is used for charging the capacitors up to a usable voltage level. This ensures that, in the event of an electricity interruption, the actuator can move at any time from its current position into the preset emergency setting position (POP).</li> <li>The duration of the pre-charging time depends mainly on the following factors:</li> <li>Duration of the voltage interruption</li> </ul>	

PF delay time (bridging time)



#### **Product features**





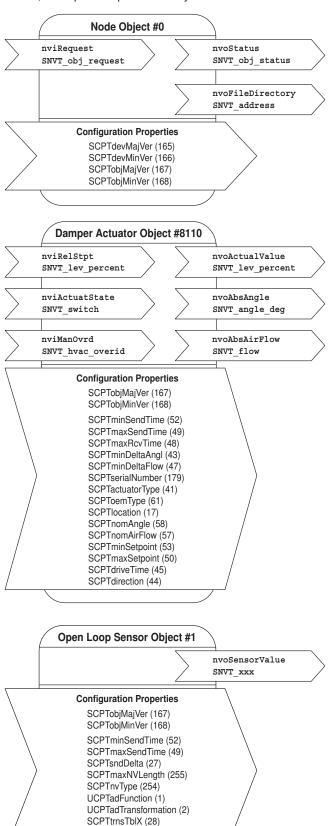
Product features	
Adaption of stroke range	The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out a stroke adaption, which is when the operating range and position feedback adjust themselves to the mechanical stroke. Manual triggering of the adaption can be carried out by pressing the "Adaption" button or with the PC-Tool.
Rotary knob emergency setting position	The "Emergency setting position" rotary knob can be used to adjust the desired emergency setting position (POP) from 0% to 100% in 10% increments. The rotary knob is in reference to the adapted or programmed height of stroke. In the event of an electricity interruption, the actuator will move into the selected emergency setting position, taking into account the bridging time (PF) of 2 s which was set ex-works. Settings: The rotary knob must be set to the "Tool" position for retroactive settings of the emergency setting position with the BELIMO service tool MFT-P. Once the rotary knob is set back to the range 0 100%, the manually set value will have positioning authority
Bridging time (PF)	Electricity interruptions can be bridged up to a maximum of 10 s. In the event of an electricity interruption, the actuator will remain stationary in accordance with the set bridging time. If the electricity interruption is greater than the set bridging time, then the actuator will move into the selected emergency setting position (POP). The bridging time set ex-works is 2 s. This can be modified at the site of operations with the use of the BELIMO service tool MFT-P. Settings: The rotary knob must not be set to the "Tool" position! Only the values need to be entered for retroactive adjustments of the bridging time with the BELIMO service tool MFT-P.

Accessories			
		Description	Туре
	Service tools	Manual parameterizing device, for MF/MP/Modbus/LonWorks actuators and VAV-Control	ZTH-GEN
		Belimo PC-Tool, software for adjustments and diagnostics	MFT-P



# Functional profile according to LONMARK®

The LON-capable actuator is certified by LONMARK®. Die following actuator functions are made available via the LONWORKS® network as standardised network variables in accordance with LONMARK®: the Node Object #0, the Damper Actuator Object #8110, the Open Loop Sensor Object #1 and the Thermostat Object #8060.



# Node Object #0

The node object contains the object status and object request functions.

# nviRequest: SNVT\_obj\_request

Input variable for requesting the status of a particular object in the node.

# nvoStatus: SNVT\_obj\_status

Output variable that outputs the current status of a particular object in the node.

#### nvoFileDirectory: SNVT\_address

Output variable that shows information in the address range of the Neuron chip.

# Damper Actuator Object #8110

The actuator object is used to display the functions of the actuator on the page of the LONWORKS® network.

#### nviRelStpt: SNVT\_lev\_percent

The nominal position is assigned to the actuator via this input variable. This variable is normally linked to the output variable of an HVAC controller.

# nviActuateState: SNVT\_switch

A preset position is assigned to the actuator via this input variable. Note on priority: The variable which was most recently active, either nviActuatorState or nviRelStpt, has priority.

#### nviManOvrd: SNVT\_hvac\_overid

This input variable can be used to manually override the actuator into a particular position.

# nvoActualValue: SNVT\_lev\_percent

This output variable shows the current actual position of the actuator and can be used for control circuit feedback or for displaying positions.

# nvoAbsAngle: SNVT\_angle\_deg

This output variable shows the current angle of rotation / stroke of the actuator and can be used to display the position or for service purposes.

# nvoAbsAirFlow: SNVT\_flow

This output variable is inactive with this actuator and shows a constant value of 65535 (this variable is only active in conjunction with LON-capable VAV controllers).

# **Open Loop Sensor Object #1**

One sensor can be connected to the actuator.

A passive resistance sensor (e.g. Ni1000), an active sensor (output 0  $\dots$  32 V) or a switch (On/Off) can be connected. In the case of the open loop sensor object, the measured sensor values are transferred to the LONWORKS® network.

# nvoSensorValue: SNVT\_xxx

This output variable shows the current sensor value. Depending on the connected sensor, the output variable can be configured via the sensor plug-in and specifically adapted to the system.

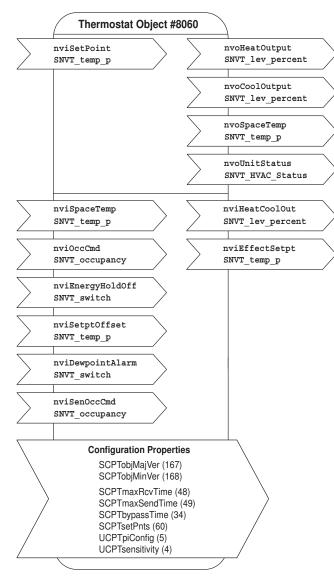
The SNVT can be configured as:		
SNVT_temp_p	SNVT_lev_percent	SNVT_lux
SNVT_temp	SNVT_abs_humid	SNVT_press_p
SNVT_switch	SNVT_enthalpy	SNVT_smo_obscur
SNVT_flow	SNVT_ppm	SNVT_power
SNVT_flow_p	SNVT_rpm	SNVT_elec_kwh

SCPTtrnsTblY (29) SCPTinvrtOut (16)



# Functional profile according to LONMARK®

Individual room control solutions can be implemented with the thermostat object LONMARK® #8060. An LNS plug-in is available for configuring the controller parameters.



# Note

A restart is necessary after accessing network variables for the purpose of rewriting them or after deleting links in order to initialise the variables.

# Thermostat Object #8060

#### nviSetPoint: SNVT\_temp\_p

Setpoint specification for the controller from the higher-level system or the room control unit. If this variable is not linked, then the local setpoints of the controller object apply (can be adjusted via plug-in). The setpoint specification from the higher-level system influences the setting on the controller as follows:

Example: Comfort setpoint for heating =  $21 \degree C$  and Comfort setpoint for cooling =  $23 \degree C$ . The median point between heating and cooling is thus  $22 \degree C$ . Now, if the external setpoint (nviSetPoint) is  $23 \degree C$ , then the heating setpoint will shift to  $22 \degree C$  and the cooling set point to  $24 \degree C$ . The setpoints for Pre-Comfort heating and cooling will also be shifted accordingly.

# nviSpaceTemp: SNVT\_temp\_p

Room temperature from external room sensor. It is imperative that this variable be linked; typically, it is linked with the variable of the sensor object.

#### nviOccCmd: SNVT\_occupancy

Occupancy specification from the command centre (for the function, see the table entitled «Functions Inputs Occupancy» next page).

#### nviEnergyHoldOff: SNVT\_switch

In the case of active EnergyHoldOff, the controller will be set to the Building Protection setpoints.

### nviSetPtOffset: SNVT\_temp\_p

Shifting of the room control unit. If the nviSetPoint is linked, then this input has an influence on the variable value of nviSetPoint, i.e. it corrects it. Otherwise, the Comfort and Pre-Comfort setpoints for heating and cooling will be adjusted directly by the amount of the shift (compare example with nviSetPoint).

# nviDewpointAlarm: SNVT\_switch

In the case of active DewpointAlarm, the controller will be set to the Building Protection setpoints. The cooling sequence is deactivated.

#### nviSenOccCmd: SNVT\_occupancy

Occupancy specification from the local occupancy switch (for the function, see the table entitled «Functions Inputs Occupancy» next page).

# nvoHeatOutput: SNVT\_lev\_percent

Control signal for heating.

#### nvoCoolOutput: SNVT\_lev\_percent

Control signal for cooling.

#### nvoSpaceTemp: SNVT\_temp\_p

Displays the room temperature of the nviSpaceTemp. If nviSpaceTemp is not linked, then the variable will display the value 0x7FFF.

#### nvoUnitStatus: SNVT\_HVAC\_Status

Displays the operating mode of the controller (in accordance with Functional Profile #8060).

#### nvoHeatCoolOut: SNVT\_lev\_percent

Depicts the heating and cooling sequence for controlling the 6-way characterised control valves (see illustration, next page).

This outlet runs parallel to the nvoCoolOutput or the nvoHeatOutput, respectively.

#### Cooling = 33 ... 0%

Valve closed 33 ... 66% Heating = 66 ... 100%

# nvoEffectSetpt: SNVT\_temp\_p

Shows the actual setpoint of the controller.

Note



# Functional profile according to LONMARK®

#### **Functions Inputs Occupancy** Occupancy specification from Occupancy switch Room operating Comfort extension nviOccCmd command nviSenOccCmd status centre OC\_OCCUPIED OC OCCUPIED Comfort OC UNOCCUPIED Comfort The function nviOccCmd has a higher priority than the function nviSenOccCmd. OC\_NUL (default) Comfort OC STANDBY OC OCCUPIED Bypass Occupied time is extended by the amount of the bypass time (comfort time) (can be adjusted in the plug-in) OC\_UNOCCUPIED Pre-Comfort OC\_NUL (default) Pre-Comfort OC\_UNOCCUPIED OC\_OCCUPIED **Building Protection** OC\_UNOCCUPIED **Building Protection** OC\_NUL (default) **Building Protection** OC\_NUL (default) OC\_OCCUPIED Comfort OC\_UNOCCUPIED Pre-Comfort OC\_NUL (default) Comfort

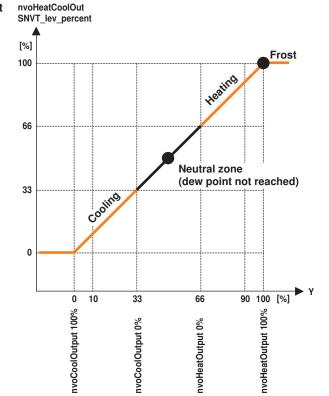
#### Funktion nvoHeatCoolOut

**Typical application** Heating / cooling with Belimo

6-way characterised control valve.

Note chilled ceiling application

In the case of active DewPointAlarm (nviDewPointAlarm), the controller will be set to the Building Protection setpoints. The cooling sequence is deactivated.



#### Notes

More detailed information on the functional profiles can be found on the website of LONMARK®. (www.lonmark.org).

# **AVK24ALON**

Globe valve actuator, communicative, modulating, AC/DC 24 V, 2000 N



ZK1-GEN

Parameterisation		
Connection of the MFT parameterising devices, e.g. Belimo PC-Tool MFT-P	<ul> <li>The actuator can be parameterised as follows:</li> <li>Electronic angle of rotation limiting / stroke limiting</li> <li>Torque reduction / stroke reduction</li> <li>Operation mode</li> <li>Running time</li> <li>Function test or adaption can be triggered</li> <li>Position feedback (measuring voltage U)</li> </ul>	
Parameterisation of the connected actuator	L ~ AC 24 V - + DC 24 V	

#### BELIMO MOL O Enable O Data O Initialia MPAN The actuator can be triggered with the PC-ISB ZIP-USB-MP ce • The USB cable is included in the ZIP-USB-| 2 3 | 5 6 • The connection cable ZK1-GEN has to be + ~ MFT LON ī

# ordered separately.

#### Parameterisation of the actuator, Standalone, without AC/DC 24V supply

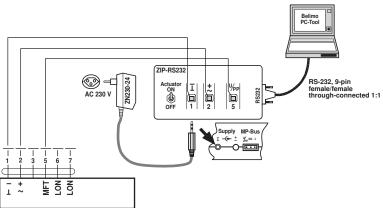
# Notes

Notes

Tool under "PP".

MP scope of delivery.

- The actuator can be triggered with the PC-Tool under "PP".
- The RS-232 cable is included in the ZIP232 scope of delivery.
- The power supply unit ZN230-24 has to be ordered separately.





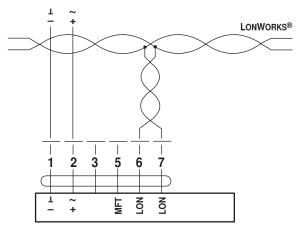
# **Electrical installation**

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- · Connection via safety isolating transformer.
  - · Direction of stroke switch factory setting: Actuator spindle retracted.

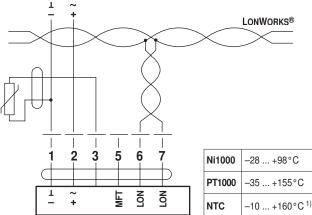
#### Wiring diagrams

#### **Connection without sensor**



Notes

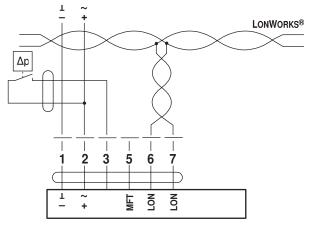
#### Connection with passive sensor, e.g. Pt1000, Ni1000, NTC



Ni1000	−28 +98°C	850 1600 $\Omega^{2)}$
PT1000	−35 +155°C	850 1600 $\Omega^{2)}$
NTC	-10 +160°C <sup>1)</sup>	$200~\Omega \ldots 50~k\Omega^{2)}$

Sensor scaling: The sensors can be scaled with the sensor plug-in (sensor table). 1) Depending on the type 2) Resolution 1 Ohm

# Connection with switching contact, e.g. Δp-monitor

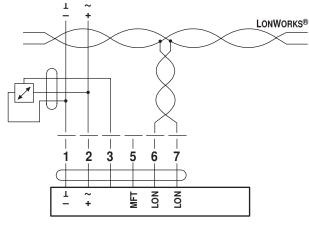


Switching contact requirements: The switching contact must be able to switch a current of 16 mA at 24V accurately.



# **Electrical installation**

Connection with active sensor, e.g. 0 ... 10V @ 0 ... 50 °C



Possible voltage range: 0 ... 32V (Resolution 30 mV) Sensor scaling: The sensors can be scaled with the sensor plug-in (sensor table)

#### Indicators and operating elements

(1) Direction of stroke switch Switching: Direction of stroke changes

- (2) Cover, POP button
- (3) POP button
- (4) Scale for manual adjustment
- (5) Position for adjustment with tool

#### (6) Service plug

For connecting the parameterisation and service tools

(7) Gear disengagement button, temporary

Press button: Gear disengages, motor stops, manual override possible Release button: Gear engages, standard mode

#### (8) Service button for commissioning with LONWORKS®

Press button: Service Pin Message is sent on LONWORKS® network

#### (9) Push-button

Press button: Switches on stroke adaption, followed by standard mode

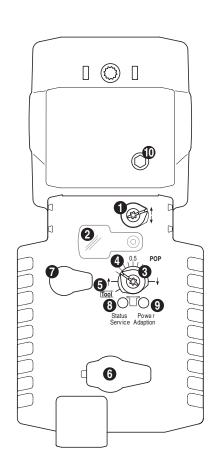
#### (**10**) Manual override Clockwise: Actuator spindle extends Counterclockwise: Actuator spindle retracts

LED displays (8, yellow) and (9, green) yellow: Off; green: Illuminated; The actuator is linked to the LONWORKS® network and ready for operation

yellow: Illuminated; green: Illuminated; No application software is loaded in the actuator yellow: Blinking (flashing interval 2 s); green: Illuminated; The actuator is ready for operation, but not linked to the LONWORKS® network (unconfigured) yellow: Off; green: Blinking; POP functions active

yellow: Illuminated; green: Off; Pre-charging time SuperCap / Fault SuperCap / Wiring error in supply

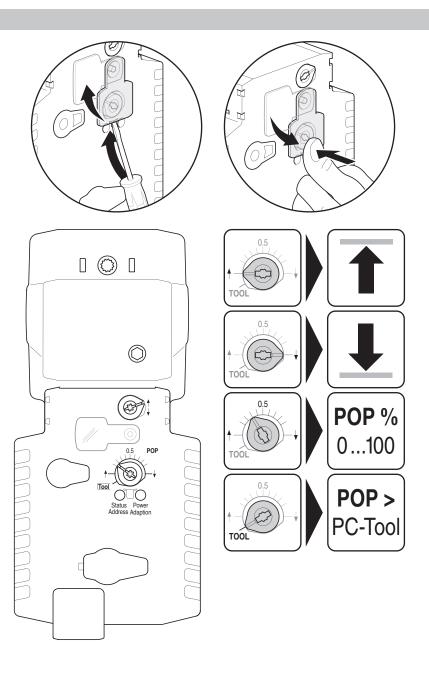
yellow: Off; green: Off; Not in operation



Globe valve actuator, communicative, modulating, AC/DC 24 V, 2000 N



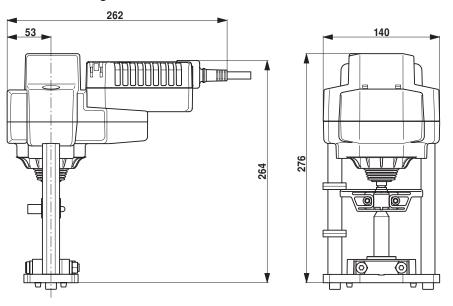
Indicators and operating elements





# **Dimensions** [mm]

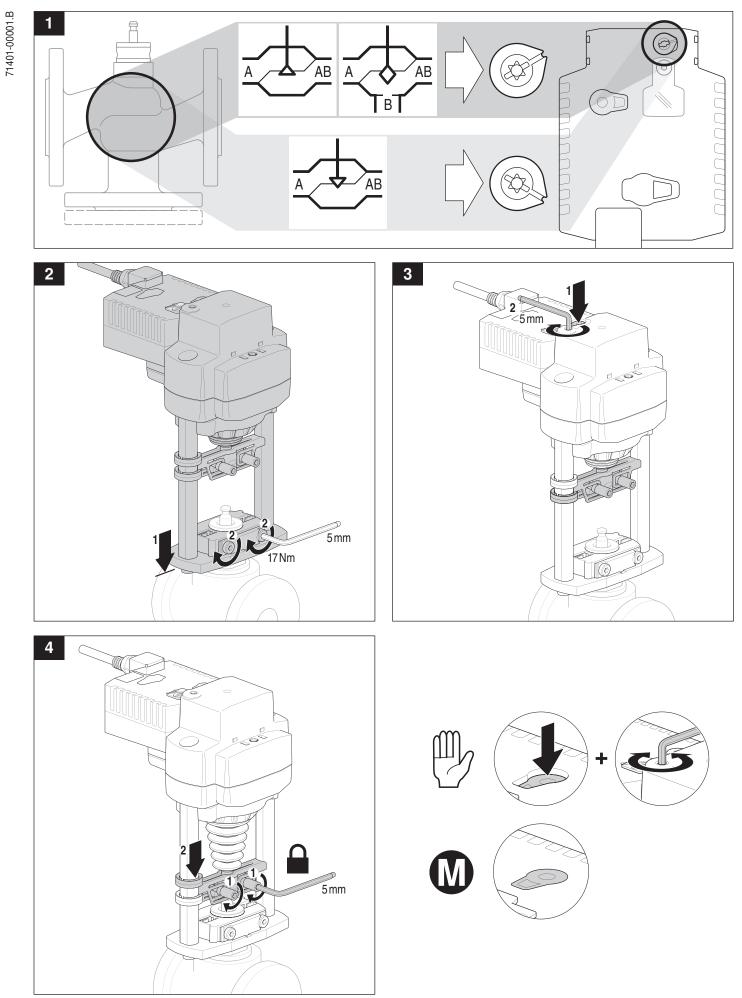
# **Dimensional drawings**



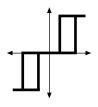
# **Further documentation**

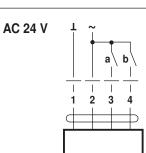
- Data sheets for globe valves
  Installation instructions for activity
- · Installation instructions for actuators and/or globe valves, respectively
- Notes for project planning, 2-way and 3-way globe valves
- Overview Valve-actuator combinations
- Description Belimo Plug-Ins





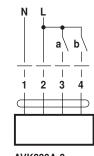






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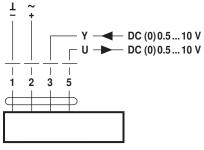
AC 24 V / DC 24 V

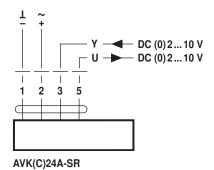


AC 230 V 🕂

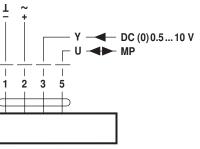
AVK230A-3

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AVK(C)24A-SZ AVK(C)24A-MF



AVK(C)24A-MP

