Multifunctional damper actuator for operating air control dampers in ventilation and air-conditioning systems for building services installations

- Air damper up to approx. $4 \mathrm{~m}^{2}$
- Torque 20 Nm
- Nominal voltage AC/DC 24 V
- Control: modulating DC 0 ... 10 V or variable
- Position feedback DC 2 ... 10 V or variable
- Running time 35 s


## Technical data

Electrical data

| Nominal voltage | AC $24 \mathrm{~V}, 50 / 60 \mathrm{~Hz} / \mathrm{DC} 24 \mathrm{~V}$ |  |  |
| :---: | :---: | :---: | :---: |
| Nominal voltage range | AC 19.2 ... 28.8 V / DC 21.6 ... 28.8 V |  |  |
| Power consumption Operation <br> At rest <br> Wire sizing | 4 W @ nominal torque 1.5 W <br> 7 VA |  |  |
| Connection | Cable $1 \mathrm{~m}, 4 \times 0.75 \mathrm{~mm}^{2}$ |  |  |
| Functional data | Factory settings | Variable | Settings |
| Torque (nominal torque) | Min. 20 Nm @ nominal voltage | 25\%, 50\%, 75\% reduced | .................... |
| Control Control signal Y Operating range | DC 0 ... 10 V , input impedance $100 \mathrm{k} \Omega$ DC 2 ... 10 V | Open-close / 3-point (only AC) <br> Starting point DC 0.5 ... 30 V <br> End point DC $2.5 \ldots 32 \mathrm{~V}$ | ...... |
| Position feedback (measuring voltage U) | DC $2 \ldots 10 \mathrm{~V}$, max. 0.5 mA | $\begin{array}{lll}\text { Starting point } & \text { DC } 0.5 \ldots 8 \mathrm{~V} \\ \text { End point } & \text { DC } 2.5 \ldots 10 \mathrm{~V}\end{array}$ | ............ |
| Position accuracy | $\pm 5 \%$ |  |  |
| Direction of rotation | Reversible with switch 0 / 1 |  |  |
| Direction of motion at $\mathrm{Y}=0 \mathrm{~V}$ | At switch position $0 \curvearrowleft$ resp. $1 \curvearrowright$ | Electronically reversible | ................ |
| Manual override | Gearing latch disengaged with pushbutton, can be locked |  |  |
| Angle of rotation | Max. $95^{\circ} \nless$, can be limited at both ends with adjustable mechanical end stops |  |  |
| Running time | $35 \mathrm{~s} / 90^{\circ}<$ | $35 . .150 \mathrm{~s}$ |  |
| Automatic adjustment of running time, operating range and measuring signal U to match the mechanical angle of rotation | Manual triggering of the adaption by pressing the „Adaption" button or with the PC-Tool | Automatic adaption whenever the supply voltage is switched on |  |
| Override control | $\begin{array}{ll} \text { MAX (maximum position) } & =100 \% \\ \text { MIN (minimum position) } & =0 \% \\ \text { ZS (intermediate position, only AC) } & =50 \% \end{array}$ | $\begin{aligned} & \text { MAX }=\left(\operatorname{MIN}+30^{\circ} \triangleleft\right) \ldots 100 \% \\ & \text { MIN }=0 \% \ldots\left(\text { MAX }-30^{\circ} \Varangle\right) \\ & Z S=\text { MIN } \ldots \text { MAX } \end{aligned}$ |  |
| Sound power level | Max. 55 dB (A) | With a $\quad 35 \mathrm{~s}=55 \mathrm{~dB}(\mathrm{~A})$ <br> running time of $150 \mathrm{~s}=35 \mathrm{~dB}(\mathrm{~A})$ |  |
| Position indication | Mechanical, pluggable |  |  |
| Safety |  |  |  |
| Protection class | III Safety extra-low voltage |  |  |
| Degree of protection | IP54 in any mounting position |  |  |
| EMC | CE according to 2004/108/EC |  |  |
| Certification | cULus according to UL 60730-1A and UL 60730-2-14 and CAN/CSA E60730-1:02 and CSA C22.2 No. 24-93 certified to IEC/EN 60730-1 and IEC/EN 60730-2-14 |  |  |
| Mode of operation | Type 1 (EN 60730-1) |  |  |
| Rated impulse voltage | 0.8 kV (EN 60730-1) |  |  |
| Control pollution degree | 3 (EN 60730-1) |  |  |
| Ambient temperature | $-30 \ldots+50^{\circ} \mathrm{C}$ |  |  |
| Non-operating temperature | $-40 \ldots+80^{\circ} \mathrm{C}$ |  |  |
| Ambient humidity | 95\% RH, non-condensating (EN 60730-1) |  |  |
| Maintenance | Maintenance-free |  |  |
| Dimensions / Weight |  |  |  |
| Dimensions | See «Dimensions» on page 4 |  |  |
| Weight | Approx. 1'060 g |  |  |

## Safety notes



- The actuator is not allowed to be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- It may only be installed by suitably trained personnel. Any legal regulations or regulations issued by authorities must be observed during assembly.
- The device may only be opened up in the factory. It does not contain any parts that can be replaced or repaired by the user.
- The cable must not be removed from the device.
- When calculating the required torque, the specifications supplied by the damper manufacturers (cross section, design, installation site), and the air flow conditions must be observed.
- The device contains electrical and electronic components and is not allowed to be disposed of as household refuse. All locally valid regulations and requirements must be observed.


## Product features

| Mode of operation | The actuator is controlled with a standard modulating signal of DC $0 \ldots 10 \mathrm{~V}$ and travels to the <br> position defined by the control signal. The measuring voltage $U$ serves for the electrical display <br> of the damper position $0 \ldots 100 \%$ and as slave control signal for other actuators. |
| ---: | :--- |
| Parameterisable actuators | The factory settings cover the most common applications. Input and output signals and other <br> parameters can be altered with the MFT-H parameterising device or the BELIMO Service Tool, <br> MFT-P. |
| Simple direct mounting | Simple direct mounting on the damper spindle with a universal spindle clamp, supplied with an <br> anti-rotation strap to prevent the actuator from rotating. |
| Manual override | Manual override with pushbutton possible (the gear is disengaged for as long as the button is <br> pressed or remains locked). |
| High functional reliability | Adjustable angle of rotation with mechanical end stops. <br> The actuator is overload-proof, requires no limit switches and automatically stops when the end <br> stop is reached. <br> Home position |
| When the supply voltage is switched on for the first time, i.e. at commissioning or after pressing <br> the „gear disengagement" switch, the actuator travels to the home position. |  |


| Pos. Direction of <br> rotation switch | Home position |  |
| :--- | :--- | :---: |
| $Q_{1}^{0} \mathrm{Y}=0 \curvearrowleft$ | $\mathrm{ccw} \curvearrowleft$ |  |
| $\mathrm{Y}=0 \curvearrowleft$ | Left stop |  |

The actuator then moves into the position defined by the control signal.

| Accessories |  |  |
| :---: | :---: | :---: |
|  | Description | Data sheet |
| Electrical accessories | Auxiliary switch S..A.. | T2 - S..A.. |
|  | Feedback potentiometer P..A.. | T2 - P..... |
|  | Manual parameterising device MFT-H | T2-MFT-H |
|  | PC-Tool MFT-P | T2 - MFT-P |
|  | Positioner SG.. 24 | T2-SG. 24 |
|  | Digital position indication ZAD24 | T2-ZAD24 |
| Mechanical accessories | Various accessories (clamps, shaft extensions etc.) | T2-Z-SM..A.. |
| Electrical installation |  |  |
| Wiring diagram |  |  |
| Note <br> - Connect via safety isolation transformer. <br> - Other actuators can be connected in parallel. Note the performance data. |  |  |

## Functions with basic values

Override control with AC 24 V
with relay contacts


Remote control 0 ... 100\%


Master/Slave control (position-dependent)


Position indication


Override control with AC 24 V
with rotary control switch


## Minimum limit



Control with 4 ... 20 mA via external resistance


The $500 \Omega$ resistor converts the 4 ... 20 mA current signal into a voltage signal DC $2 \ldots 10 \mathrm{~V}$

Functional check


## Procedure

- Apply AC 24 V to connection 1 and 2
- Disconnect connection 3:
- For direction of rotation 0:

Actuator turns in the direction of

- For direction of rotation 1 :

Actuator turns in the direction of $\curvearrowright$

- Short circuit connections 2 and 3 :
- Actuator runs in the opposite direction

Functions for actuators with specific parameters

Override control and limiting with AC 24 V with relay contacts


Override control and limiting with AC 24 V with rotary switch

${ }^{1)}$ Caution! This function is only guaranteed if the start point of the operating range is defined as min. 0.6 V .


## Dimensions [mm]

Dimensional drawings


| Damper spindle | Length | OI | $\square I$ | $\boxed{ } I$ |
| :---: | :---: | :---: | :---: | :---: |
| $\square$ | $\geq 48$ | $10 \ldots 20$ | $\geq 10$ | $\leq 20$ |
|  | $\geq 20$ | $10 \ldots 20$ | $\geq 10$ | $\leq 20$ |



## Operating controls and indicators


(1) Direction of rotation switch

Switching over:: Direction of rotation changes
(2) Push-button and green LED display
$\begin{array}{ll}\text { Off: } & \text { No voltage supply or fault } \\ \text { On: } & \text { Operation } \\ \text { Press button: } & \text { Switches on angle of rotation adaptation followed by standard operation }\end{array}$
(3) Pushbutton and yellow LED display

Off: Standard operation
On: Adaptation or synchronising process active
Press button: No function
(4) Gear disengagement switch

Press button: Gear disengaged, motor stops, manual override possible
Release button: Gear engaged, synchronisation starts, followed by standard operation
(5) Service plug

For connecting parameterising and service tools
Check connection power supply
$\left.\begin{array}{ll}\text { (2) } & \text { Off } \\ \text { (3) } & \text { On }\end{array}\right\}$ or $\left.\begin{array}{c}\text { flashing } \\ \text { flashing }\end{array}\right\}$ Check the power supply connections. $£$ and $\tilde{+}$ could be reverse.


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AC 24 V / DC 24 V


SM24A..
AC $100 \ldots 240$ V


SM230A..


SM24A-S..


SM230A-S..


SM24AP5..



SM24A-MP..

AC $100 \ldots 240$ V



SM230A-V / VR..

